

# Propeller C Compiler User's Manual

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By Mike Christle

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## Introduction

Does the world need another compiler? Probably not. However, I took a course in compiler design a couple of years ago and found the subject absolutely fascinating. Since then I have had a lot of fun working on this little project. If anyone else finds it useful, well that's good to.

PropC is a command line compiler that outputs Parallax Propeller assembly code. The source language is based on C. Rather than trying to be C compliant; my priority was to allow efficient access to all the unique features of the Propeller. That's why I added many functions and expressions that are simple wrappers around Propeller assembly instructions.

I recently started using the Parallax SimpleIDE. So I added an assembler that outputs a text file that can be included in the main C program.

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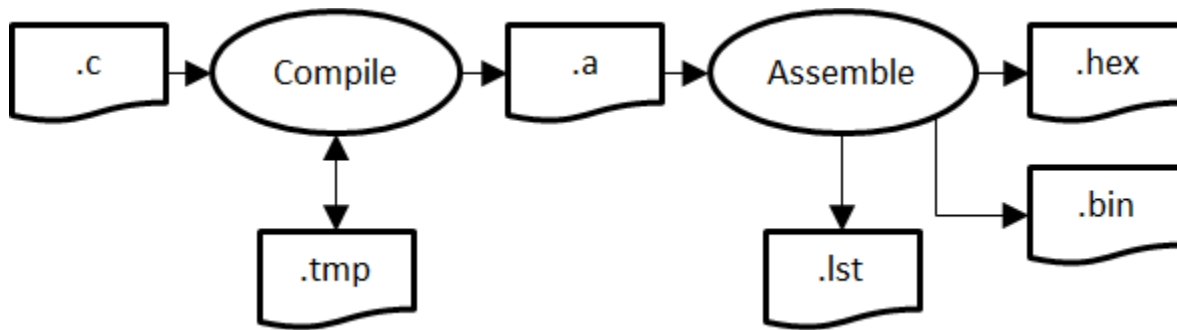
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## Build Process



The `.c` file is your PropC source. The `.tmp` file is created and used by the compiler; it contains the source for all included source files. The `.a` file contains the Propeller assembly source. The `.a` file can be assembled with the Propeller Tool, or passed to the PropC assembler. The `.hex` file contains the object code as C syntax hexadecimal constants. Use the `#header` and `#footer` directives to make this file an initialized integer array. The `.lst` file is an optional list file.

Optionally, a binary `.bin` file can be output instead of the `.hex` file. The binary file can be read into a Spin file using the Spin `FILE` command.

The first function encountered will become the main function regardless of the name. This function should loop forever.

PropC is not case sensitive. For example `NAME` = `Name` = `name`. This applies to all symbols and keywords.

## Command Line Options

- `-l` Output assembly list file.
- `-b` Output binary file instead of hex file.
- `-sa` Skip assembler stage.
- `-sc` Skip compiler stage, pass file directly to assembler.
- `-so` Skip optimizer, useful if object code is in doubt.

## Directives

- |                                  |  |
|----------------------------------|--|
| <code>#include "filename"</code> | Include the named file.                                      |
| <code>#define label value</code> | Define constants   |
| <code>#header "text"</code>      | Text is written to the top of the <code>.hex</code> file.    |
| <code>#footer "text"</code>      | Text is written to the bottom of the <code>.hex</code> file. |

## Error Reporting

PropC will stop on the first error and output a (hopefully useful) error message and the source line number. The line number refers to the `.tmp` file which is a composite of all included source files. If no files are included then this is the same as the `.c` file.

## Language Syntax

All of the examples are snippets from .a files of test cases. That's why the C code appears as assembly comments.

## Comments

PropC supports line comments, `//`. It does not support block comments, `/* */`.

## Data Types

Int UInt            32 bit signed and unsigned integers.

Real                32 bit fixed point number, with 16 bits on either side of the decimal point.

## Constants

Constants are specified similar to C, they start with a digit and the default is decimal. The 0x, 0o, and 0b prefixes specify hexadecimal, octal, and binary formats respectively. If the constant contains a period it is interpreted as a real data type, otherwise it is interpreted as an integer. Constants may include underscores which are ignored.

## Predefined Constants

The following constants are always defined. Type AINT means int or uint.

Name	Value	Type	Description
true	1	AINT	TRUE
false	0	AINT	FALSE
odd	1	AINT	Used with parity function.
even	0	AINT	Used with parity function.
dira		UINT	Propeller register.
dirb		UINT	Propeller register.
ina		UINT	Propeller register.
inb		UINT	Propeller register.
outa		UINT	Propeller register.
outb		UINT	Propeller register.
par		UINT	Propeller register.
cnt		UINT	Propeller register.
ctra		UINT	Propeller register.
ctrb		UINT	Propeller register.
frqa		UINT	Propeller register.
frqb		UINT	Propeller register.
phsa		UINT	Propeller register.
phsb		UINT	Propeller register.
vcfg		UINT	Propeller register.
vscl		UINT	Propeller register.

## Assembly Language Variable Names

Function names and global variables have the same name in the assembly code output. Function variable names are constructed by appending the function name, an underscore, and the variable name. For example a variable `x` declared in the main function will get the name `main_x`. Temporary variables are constructed by appending the function name, two underscores, and an integer, for example `main__0`.

## Variable Declaration

Variables are declared as in C. They can be initialized with a constant value of the same data type.

```
'      int  i1, i2 = -4;
                                MOV      main_i2, CONST_M_4
'      uint u1, u2 = 8;
                                MOV      main_u2, #8
'      real r1, r2 = 4.4;
                                MOV      main_r2, CONST_4_4

CONST_M_4                      LONG      -4
CONST_4_4                      LONG      288358
main_i1                        RES        1
main_i2                        RES        1
main_u1                        RES        1
main_u2                        RES        1
main_r1                        RES        1
main_r2                        RES        1
```

## Expressions Operators

Expressions can be constructed using these operators. They are listed in order of precedence.

Operator	Assignment	Description
()		Parentheses.
+ - ~ !		Unary plus, minus, bitwise not, logical not.
* / %	*= /= %/	Multiply, divide, modulo.
+ -	+= -=	Addition, subtraction.
<< >> <- ->	<<= >>= <-= ->=	Shift left, shift right, rotate left, rotate right.
& &~	&= &~=	Bitwise and, bitwise and not.
^	^=	Bitwise exclusive or.
	=	Bitwise or.
<# #>		Max, min.

### Rotate

Rotates work just like shifts. Rotates have the same level of precedence as shifts.

'	a = b <- c;	MOV	main_a, main_b
		ROL	main_a, main_c
'	a = b -> 5;	MOV	main_a, main_b
		ROR	main_a, #5
'	a <-= 4;	ROL	main_a, #4
'	a ->= b;	ROR	main_a, main_b

### AndNot

'	uint pin_mask;		
'			
'	// Set a pin HI		
'	outa  = pin_mask;		
		OR	outa, main_pin_mask
'	// Set a pin LO		
'	outa &~= pin_mask;		
		ANDN	outa, main_pin_mask

### Limits

Limits get the lowest precedence level, so they work best when added to the end of an expression. Limits can be applied to expressions of any type.

'	int a, b, c;		
'	a = b + c #> 10 <# 100;		
		MOV	main_a, main_b
		ADDS	main_a, main_c
		MINS	main_a, #10
		MAXS	main_a, #100

## Logical Operators

Logical expressions can be constructed using these operators. They are listed in order of precedence.

Operator	Description
<code>==</code> <code>!=</code> <code>&lt;</code> <code>&gt;</code> <code>&lt;=</code> <code>&gt;=</code>	Compare two expressions, or compare one expression to 0.
<code>LOCKSET</code>	Set and test a lock.
<code>LOCKCLR</code>	Clear and test a lock.
<code>PARITY</code>	Test parity of an expression.
<code>&amp;&amp;</code>	Logical and.
<code>  </code>	Logical or.

## Locks

Function	Input Type	Output Type
<code>locknew</code>	Uint	
<code>lockset</code>	Uint	Uint
<code>lockclr</code>	Uint	Uint
<code>lockret</code>	Uint	

```
'    uint lock, data_ready, data_ptr;
'
'    locknew(lock);
'                                LOCKNEW main_lock
'
'    // Block until lock is free
'    while (lockset(lock) == true);
:L1
'                                LOCKSET main_lock WC
IF_C                                JMP    #:L1
'    // ...
'    lockclr(lock);
'                                LOCKCLR main_lock WC
'
'    // Proceed if data is ready and lock is free
'    if (data_ready && lockset(lock) == false)
'                                CMP     main_data_ready, #0    WZ
IF_Z                                JMP     #:L5
'                                LOCKSET main_lock WC
IF_C                                JMP     #:L5
'    {
'        // ...
'        lockclr(lock);
'                                LOCKCLR main_lock WC
:L5
'    }
'
'    lockret(lock);
'                                LOCKRET main_lock
```



## If Statements

The syntax of the if statements is the same as C.

```
'    int a, b, c;
'
'    if (a == 3 || b == 4 && c == 5) nop;
'                                CMPS    main_a, #3    WZ
IF_Z                            JMP      #:L142
'                                CMPS    main_b, #4    WZ
IF_NZ                           JMP      #:L145
'                                CMPS    main_c, #5    WZ
IF_NZ                           JMP      #:L145
:L142
'                                NOP
:L145
'
'    if (a == b)
'                                CMPS    main_a, main_b  WZ
IF_NZ                           JMP      #:L154
'    {
'        a = 9;
'                                MOV      main_a, #9
'                                JMP      #:L155
'    }
'    else
'    {
:L154
'        a = 6;
'                                MOV      main_a, #6
:L155
'    }
```

## For Loops

The syntax of for loops is the same as C, except that the test and increment clauses are optional. The abbreviated form takes advantage of the DJNZ instruction. The break and continue statements work as expected.

```
'  int i, j, k;
'  for (i = j + 10)
'      MOV      main_i, main_j
'      ADDS     main_i, #10
'      k += 4;
:L1      ADDS     main_k, #4
'      DJNZ     main_i, #:L1
'
'  for (i = 0; i < 10; i += 1)
'      MOV      main_i, #0
:L3      CMPS     main_i, #10  WZ, WC
'      IF_NC     JMP      #:L6
'      {
'          if (i == 3) continue;
'          CMPS     main_i, #3  WZ
'          IF_Z     JMP      #:L3
'          if (i == 7) break;
'          CMPS     main_i, #7  WZ
'          IF_Z     JMP      #:L6
'          }
'          ADDS     main_i, #1
'          JMP      #:L3
:L6
```

## While Loops

The syntax for the while and do while loops is the same as in C.

```
'      int i, j;
'      while (true) nop;
:L1
                                NOP
                                JMP      #:L1
'
'      while (i < 40)
:L4
                                CMPS     main_i, #40  WZ, WC
IF_NC                                JMP      #:L6
'      {
'          if (i == 10) continue;
                                CMPS     main_i, #10  WZ
IF_Z                                JMP      #:L4
'          if (i == 20) break;
                                CMPS     main_i, #20  WZ
IF_NZ                               JMP      #:L4
:L6
'      }
'
'      do
:L13
'      {
'          if (i == 10) continue;
                                CMPS     main_i, #10  WZ
IF_Z                                JMP      #:L13
'          if (i == 20) break;
                                CMPS     main_i, #20  WZ
IF_Z                                JMP      #:L14
'      }
'      while (i < 40);
                                CMPS     main_i, #40  WZ, WC
IF_C                                JMP      #:L13
:L14
```

## Switch

The syntax for the switch statement is the same as in C. The switch variable must be an integer type. The case values must be integer constants.

```
'      int i, j;
'      uint m;
'      switch (i)
'      {
'          case 1: j += 3; break;
'                  CMPS    main_i, #1    WZ
IF_NZ      JMP      #:L2
'                  ADDS    main_j, #3
'                  JMP      #:L1
:L2
'          case 2: j -= 5; break;
'                  CMPS    main_i, #2    WZ
IF_NZ      JMP      #:L3
'                  SUBS    main_j, #5
'                  JMP      #:L1
:L3
'          default: j = 0; break;
'                  MOV     main_j, #0
'      }
:L1
'
'      switch (m)
'      {
'          case 1: j += 3; break;
'                  CMP     main_m, #1    WZ
IF_NZ      JMP      #:L5
'                  ADDS    main_j, #3
'                  JMP      #:L4
:L5
'          case 2: j -= 5; break;
'                  CMP     main_m, #2    WZ
IF_NZ      JMP      #:L6
'                  SUBS    main_j, #5
'                  JMP      #:L4
:L6
'          default: j = 0; break;
'                  MOV     main_j, #0
'      }
:L4
```

## Functions

The syntax for function declarations and calls is the same as in C.

```
' int g1;
' void main()
' {
main
'     int i;
'     func1();
'
'     CALL    #func1
'     i = func2(1, 5);
'
'     MOV     func2_a, #1
'     MOV     func2_b, #5
'     CALL    #func2
'     MOV     main_i, func2_
' }
main_RET      RET
'-----
' void func1()
' {
func1
'     g1 += 3;
'
'     ADDS    g1, #3
' }
func1_RET     RET
'-----
' int func2(int a, int b)
' {
func2
'     return a + b;
'
'     MOV     func2_, func2_a
'     ADDS    func2_, func2_b
' }
func2_RET     RET
'-----
```

## Built In Functions

The following functions, as well as multiply, divide and modulus, are implemented by subroutines that are included as needed. Parameters are passed to these functions via the variables math\_p1 and math\_p2. Results are passed back via the variables math\_r1 and math\_r2. The multiply, divide and modulus operations take 32 bit parameters and return 32 bit results. For the trig functions a full circle contains 512.0 degrees.

Function	Input Type	Output Type
sin	Real	Real
cos	Real	Real
tan	Real	Real
asin	Real	Real
acos	Real	Real
sqrt	Real	Real
isqrt	Int, Uint	Int, Uint
log	Any	Int
exp	Int	Int

```
'    int i, j;
'    real m, n;
'    i *= j;
                                MOV    math_p1, main_i
                                MOV    math_p2, main_j
                                CALL    #IMultiply
                                MOV    main_i, math_r1
'    i /= j;
                                MOV    math_p1, main_i
                                MOV    math_p2, main_j
                                CALL    #SDivide
                                MOV    main_i, math_r1
'    i %= j;
                                MOV    math_p1, main_i
                                MOV    math_p2, main_j
                                CALL    #SDivide
                                MOV    main_i, math_r2
'    m = sin(n);
                                MOV    math_p1, main_n
                                CALL    #Sin
                                MOV    main_m, math_r1
```

## Math Functions

Function	Input Type	Output Type
itor	Int	Real
rtoi	Real	Int
floor	Real	Real
ceil	Real	Real
trunc	Real	Real
round	Real	Real
fract	Real	Real
abs	Any	Same as input
absn	Any	Same as input

```

'    real m, n;
'    i = rtoi(m);
                                MOV    main_i, main_m
                                SAR    main_i, #16
'    m = itor(i);
                                MOV    main_m, main_i
                                SHL    main_m, #16
'    m = floor(n);
                                MOV    main_m, main_n
                                ANDN   main_m, math_real_mask
'    m = ceil(n);
                                MOV    main_m, main_n
                                ADD    main_m, math_real_mask
                                ANDN   main_m, math_real_mask
'    m = trunc(n);
                                MOV    main_m, main_n
                                ABS    main_m, main_m
                                ANDN   main_m, math_real_mask
                                NEGC   main_m, main_m
'    m = round(n);
                                MOV    main_m, main_n
                                ADD    main_m, math_half
                                ANDN   main_m, math_real_mask
'    m = fract(n);
                                MOV    main_m, main_n
                                ABS    main_m, main_m
                                AND    main_m, math_real_mask
                                NEGC   main_m, main_m
'    m = abs(n);
                                ABS    main_m, main_n
'    m = absn(n);
                                ABSNEG main_m, main_n
math_real_mask                LONG    65535

```

## Waits

These functions provide access to the Propellers four wait instructions.

```
'  uint a, one_msec, mask;
'
'  waitcnt(cnt + one_msec);
'                                MOV      main__0, cnt
'                                ADD      main__0, main_one_msec
'                                WAITCNT  main__0, #0
'  waitcnt(a, one_msec);
'                                WAITCNT  main_a, main_one_msec
'
'  waitpeq(a, 4);
'                                WAITPEQ  main_a, #4
'  waitpeq(a, mask);
'                                WAITPEQ  main_a, main_mask
'
'  waitpne(a, 8);
'                                WAITPNE  main_a, #8
'  waitpne(a, mask);
'                                WAITPNE  main_a, main_mask
'
'  waitvid(a, 9);
'                                WAITVID  main_a, #9
'  waitvid(a, mask);
'                                WAITVID  main_a, main_mask
```



## Global Data Access

Global data is modelled as four arrays: GBYTE, GWORD and GLONG. The index for these arrays must be int or uint type. Any type can be read or written.

```
'    uint uval, index;
'    int ival;
'    real rval;
'
'    uval = GBYTE[index];
'                                RDBYTE    main_uval, main_index
'    ival = GWORD[index];
'                                RDWORD    main_ival, main_index
'    rval = GLONG[index];
'                                RDLONG    main_rval, main_index
'
'    GBYTE[index] = uval;
'                                WRBYTE    main_uval, main_index
'    GWORD[index] = ival;
'                                WRWORD    main_ival, main_index
'    GLONG[index] = rval;
'                                WRLONG    main_rval, main_index
```

## Field Access

The Inst, Src and Dest fields of a register can be accessed using the .I, .S and .D qualifiers on an assignment.

```
'    uint apin, bpin;
'    CTRA.S = apin;
'                                MOVS      ctra, main_apin
'    CTRA.D = bpin;
'                                MOVD      ctra, main_bpin
'    CTRA.I = 0b0_00100_000;
'                                MOVI      ctra, #32
```

## Parity

This function will return the parity of a value. The constants ODD and EVEN are predefined for testing parity.

```
'    uint i, j, mask;
'    i = parity(mask, j);
'                                TEST      main_mask, main_j   WC
'                                SUBX      main_i, main_i
'
'    if (parity(mask, ina) == ODD) nop;
'                                TEST      main_mask, ina      WC
'    IF_NC                        JMP      #:L17
'                                NOP
:L17
```

## Miscellaneous Functions

These were included for completeness sake. Nop is useful for adding a 4 clock cycle delay.

```
'      nop;  
      NOP  
'      cmpsub(ival, 100);  
      CMPSUB  main_ival, #100  
'      rev(ival, 16);  
      REV     main_ival, #16
```

## BlinkLED Example Program

This is the main program that compiles in SimpleIDE. It includes the cog code from the file BlinkLED\_cog.hex.

```
// File BlinkLED.c
#include "simpletools.h"
#include "BlinkLED_cog.hex"

typedef struct
{
    volatile int pin_mask;
    volatile int half_period;
    int cog;
}
blink_t;

int main()
{
    int cog;
    blink_t *device;

    device = (void *) malloc(sizeof(blink_t));
    device->pin_mask = 1;
    device->half_period = CLKFREQ >> 3;

    cog = 1 + cognew((void*)cog_code, (void *)device);

    while(1);
}
```

This is the main program in Spin that runs in Propeller Tool. It includes the cog code from the file BlinkLED\_cog.bin. The cog code must be compiled with the `-b` option.

```
CON
    _clkmode = xtall + pll16x
    _xinfreq = 5_000_000

VAR
    long Cog, PinMask, HalfPeriod

PUB MainRoutine
    PinMask := 1
    HalfPeriod := 20_000_000

    Cog := cognew(@CogCode, @PinMask)
    repeat

DAT
    CogCode      file "BlinkLED_cog.bin"
```

This is the code to be compiled by PropC which runs in the cog.

```
// File BlinkLED_cog.c

#header "int cog_code[] = {"
#footer "};"

uint half_period;
uint pin_mask;
uint wait_cntr;

void main()
{
    uint ptr;

    ptr = par;
    pin_mask = GLONG[ptr];
    ptr += 4;
    half_period = GLONG[ptr];

    dira = pin_mask;
    wait_cntr = cnt + half_period;

    while (true)
    {
        outa ^= pin_mask;
        waitcnt(wait_cntr, half_period);
    }
}
```

This is the file BlinkLED\_cog.hex, which is included into the SimpleIDE file.

```
int cog_code[] = {
0xA0BC1DF0,0x08BC180E,0x80FC1C04,0x08BC160E,
0xA0BFEC0C,0xA0BC1BF1,0x80BC1A0B,0x6CBFE80C,
0xF8BC1A0B,0x5C7C0007,0x5C7C0000};
```

## BNF Grammar

<abc>	Rule name
::=	Is defined by
	Or
[]	Optional
{ }	Repeat one or more times
{ }*	Repeat zero or more times
( )	Group
' , '	Literal symbol
ABC	Keyword
;	Rule terminator

```

<program> ::= { <data-decl-stmt> | <func-decl> }* ;

<func-decl> ::= <return-data-type> <identifier>
                '(' [ <func-parms> ] ')' <func-body> ;

<func-parms> ::= <data-type> <identifier>
                { ',' <data-type> <identifier> }* ;

<return-data-type> ::= <data-type> | VOID ;

<func-body> ::= '{' { <data-decl-stmt> }* { <statement> } '}' ;

<data-decl-stmt> ::= <data-type> <data-decl> { ',' <data-decl> }* ';' ;

<data-decl> ::= <identifier> [ '=' [ '+' | '-' ] <constant> ] ;

<data-type> ::= INT | UINT | REAL ;

<statement> ::= <assignment-stmt>
                | <function-stmt>
                | <dot-assign-stmt>
                | <if-stmt>
                | <while-stmt>
                | <do-while-stmt>
                | <for-stmt>
                | <switch-stmt>
                | <break-stmt>
                | <continue-stmt>
                | <return-stmt>
                | <compound-stmt>
                | <global-array-stmt>
                | <wait-count-stmt>
                | <wait-stmt>
                | <lock-stmt>
                | <built-in-op-stmt>

```

```

    | <nop-stmt>
    | ';' ;

<assignment-stmt> ::= <assignment> ';' ;

<assignment> ::= <identifier> <assignment-op> <expr>
    | <identifier> '=' [TRUE | FALSE] ;

<assignment-op> ::= '=' | '+=' | '-=' | '*=' | '/=' | '%='
    | '|=' | '&=' | '^=' | '&~='
    | '<=>' | '>>=' | '<--=' | '->=' ;

<dot-assign-stmt> ::= <identifier> ( '.I' | '.D' | '.S' )
    '=' <expr> ';' ;

<global-array-stmt> ::= <global-array> '=' <expr> ';' ;

<global-array> ::= ( GBYTE | GWORD | GLONG ) '[' <expr> ']' ;

<if-stmt> ::= IF '(' <logical-or-expr> ')' <statement>
    [ ELSE <statement> ] ;

<while-stmt> ::= WHILE '(' <logical-or-expr> ')' <statement> ;

<do-while-stmt> ::= DO <statement>
    WHILE '(' <logical-or-expr> ')' ';' ;

<for-stmt> ::= FOR '(' <for-init>
    [ ';' <logical-or-expr> ';' <for-incr> ] ')'
    <statement> ;

<for-init> ::= <identifier> '=' <expr> ;

<for-incr> ::= <identifier> <assignment-op> <expr> ;

<switch-stmt> ::= SWITCH '(' <expr> ')'
    '{' { <case-clause> }* [<default-clause>] '}' ;

<case-clause> ::= CASE <integer-constant> ':' { <statement> }* BREAK ';' ;

<default-clause> ::= DEFAULT ':' { <statement> }* BREAK ';' ;

<break-stmt> ::= BREAK ';' ;

<continue-stmt> ::= CONTINUE ';' ;

<return-stmt> ::= RETURN [<expr>] ';' ;

<function-stmt> ::= <function-call> ';' ;

<function-call> ::= <identifier>
    '(' [ <expr> { ',' <expr> }* ] ')' ;

```

```

<wait-count-stmt> ::= WAITCNT '(' <identifier> ',' <expr> ')' ';'
                    | WAITCNT '(' <expr> ')' ';' ;

<wait-stmt> ::= ( WAITPEQ | WAITPNE | WAITVID )
                '(' <expr> ',' <expr> ')' ';' ;

<lock-stmt> ::= ( LOCKNEW | LOCKSET | LOCKCLR | LOCKRET )
                '(' <IDENTIFIER> ')' ';' ;

<built-in-op-stmt> ::= ( CMPSUB | REV )
                       '(' <identifier> ',' <expr> ')' ';' ;

<compound-stmt> ::= '{' { <statement> } '}' ;

<nop-stmt> ::= NOP ';' ;

<logical-or-expr> ::= <logical-and-expr>
                    | <logical-or-expr> '||' <logical-and-expr> ;

<logical-and-expr> ::= <relational-expr>
                     | <logical-and-expr> '&&' <relational-expr> ;

<relational-expr> ::= <expr> '==' <expr>
                    | <expr> '!=' <expr>
                    | <expr> '<' <expr>
                    | <expr> '>' <expr>
                    | <expr> '<=' <expr>
                    | <expr> '>=' <expr>
                    | <lock-expr>
                    | <parity-expr> ;

<lock-expr> ::= ( LOCKSET | LOCKCLR ) '(' <identifier> ')'
               ( '==' | '!=' ) ( TRUE | FALSE ) ;

<parity-expr> ::= <parity-function> ( '==' | '!=' ) ( ODD | EVEN ) ;

<expr> ::= <inclusive-or-expr>
          | <expr> '#>' <inclusive-or-expr>
          | <expr> '<#' <inclusive-or-expr> ;

<inclusive-or-expr> ::= <exclusive-or-expr>
                     | <inclusive-or-expr> '|' <exclusive-or-expr> ;

<exclusive-or-expr> ::= <and-expr>
                     | <exclusive-or-expr> '^' <and-expr> ;

<and-expr> ::= <shift-expr>
              | <and-expr> '&' <shift-expr>
              | <and-expr> '&~' <shift-expr> ;

<shift-expr> ::= <additive-expr>

```

```

| <shift-expr> '<<' <additive-expr>
| <shift-expr> '>>' <additive-expr>
| <shift-expr> '->' <additive-expr>
| <shift-expr> '<-' <additive-expr> ;

<additive-expr> ::= <multiplicative-expr>
| <additive-expr> '+' <multiplicative-expr>
| <additive-expr> '-' <multiplicative-expr> ;

<multiplicative-expr> ::= <unary-expr>
| <multiplicative-expr> '*' <unary-expr>
| <multiplicative-expr> '/' <unary-expr>
| <multiplicative-expr> '%' <unary-expr> ;

<unary-expr> ::= <primary-expr>
| ! <primary-expr>
| ~ <primary-expr>
| - <primary-expr>
| + <primary-expr> ;

<primary-expr> ::= <identifier>
| <function-call>
| <global-array>
| <built-in-function>
| <parity-function>
| <built-in-operation>
| <integer-constant>
| <real-constant>
| '(' <expr> ')' ;

<built-in-function> ::= ( SIN | COS | TAN | ASIN | ACOS | LOG | EXP
| SQRT | ISQRT ) '(' <expr> ')' ;

<built-in-operation> ::= ( ABS | ABSN | ITOR | RTOI | CEIL | FLOOR
| TRUNC | ROUND | FRACT ) '(' <expr> ')' ;

<parity-function> ::= PARITY '(' <expr> ',' <expr> ')' ;

<identifier> ::= <letter> { <letter> | <digit> | '_' } * ;

<letter> ::= (a-zA-Z) ;

<digit> ::= (0-9) ;

<constant> ::= <integer-constant> | <real-constant> ;

<real-constant> ::= <dec-constant> '.' [ <dec-constant> ] ;

<integer-constant> ::= <dec-constant> | <hex-constant>
| <oct-constant> | <bin-constant> ;

<dec-constant> ::= { 0-9 | _ } ;

```



<hex-constant> ::= '0x' { 0-9 | A-F | \_ } ;

<oct-constant> ::= '0o' { 0-7 | \_ } ;

<bin-constant> ::= '0b' { 0 | 1 | \_ } ;